

# ISHM Decision Analysis Tool

## IDAT

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# Mission

Develop and provide a demonstration of an operations concept for assisting a spacecraft crew in making informed optimal decisions in the face of uncertainty.

Crew = on-board crew  
= ground-based crew

Uncertainty = uncertain cause  
= variable context

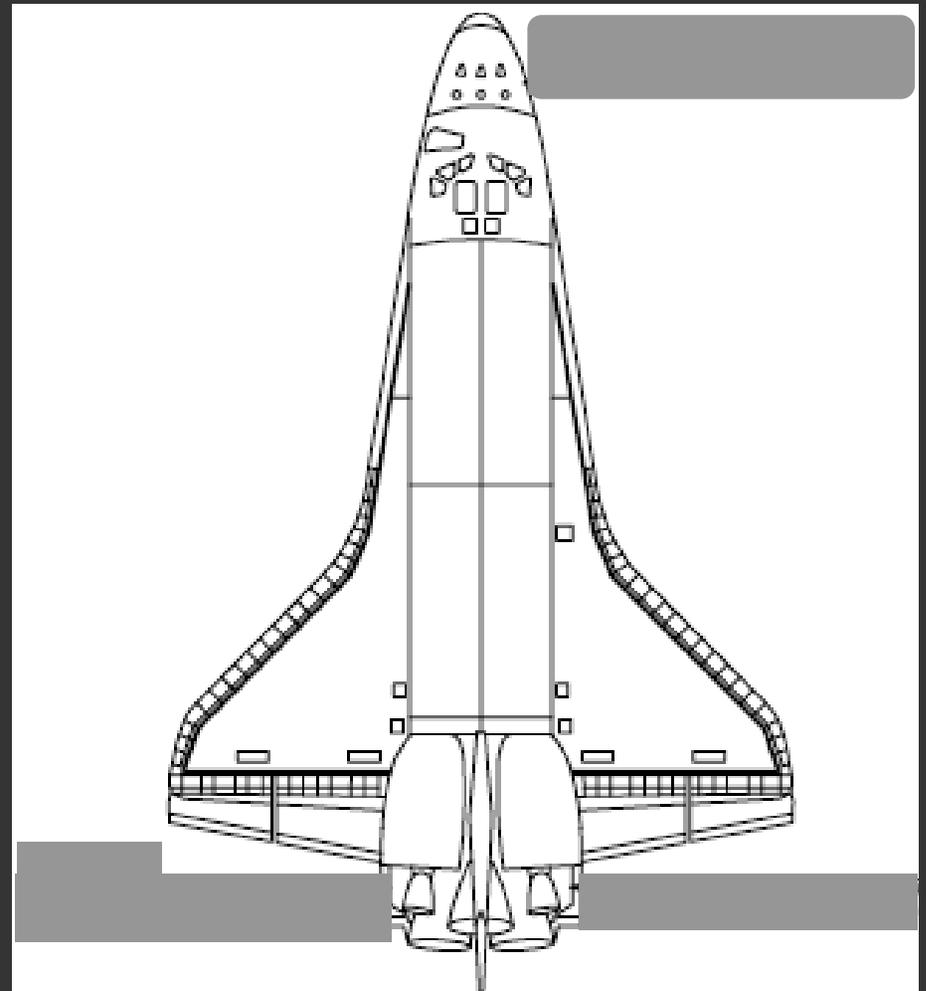
# Agenda

- Domain
- Current State of Practice
- IDAT Tool
  - Interaction Overview
  - Subsystem Details
- Future Work
- Scenario
- Demo

# Domain

## Reaction Control System (RCS)

- Rotational movement
  - Attitude control
- Translational movement
  - Velocity change
- Used alone or with MPS or OMS
- Minimum number jets required
- Hypergolic propellants

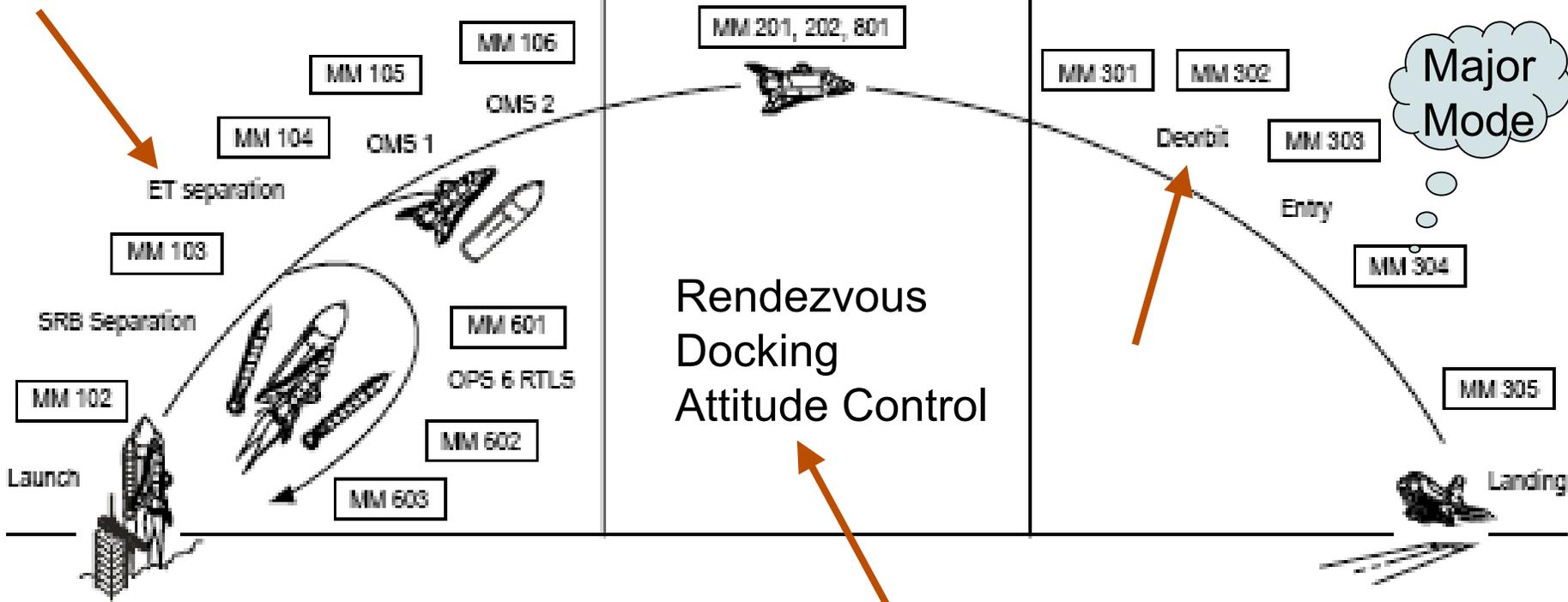


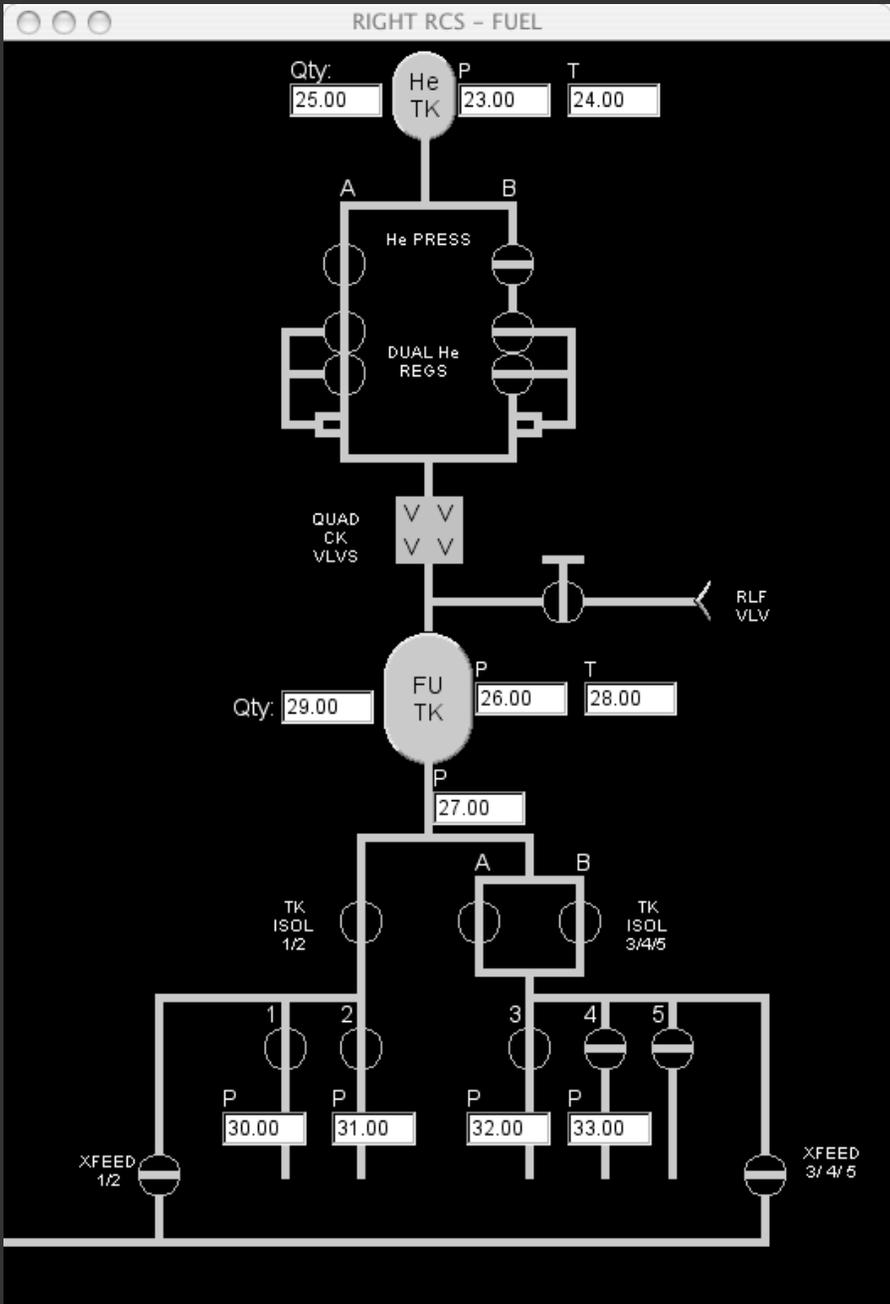
Operational Sequence

OPS 1 ASCENT

OPS 2 ORBIT  
(OPS 8 FCS CHECKOUT)

OPS 3 ENTRY





# State of Practice

1031/ /019 GNC SYS SUMM 2 5 000/00:03:34

BFS 000/00:00:00

OMS AFT QTY L R				OMS L R				
		OXID	30.1	30.1	TK P	HE	3700	3730
		FU	30.1	30.1		OXID	282	280
	FU INJ T		79	79		FU	280	277
RCS		OXID	FU	JET FAIL	ISOL VLV	N2 TK P		
FWD	HE P	3245	3398			2190	2180	
	TK P	267	271			REG P	326	329
	QTY	96	96			P VLV	OP	OP
MANF	1 P	268	269			ENG IN P		
	2 P	267	270			OXID	280	281
	3 P	266	270			FU	277	280
	4 P	267	272			VLV 1 -	2	- 2
	5					2	0	0
		OXID	FU	JET FAIL	ISOL VLV			
AFT	HE P	3408	3432			HE P	3400	3408
L	TK P	270	267			R TK P	266	269
	QTY	1	100			QTY	100	100
MANF	1 P	268	260			1 P	268	266
	2 P	270	278			2 P	266	272
	3 P	268	270			3 P	272	270
	4 P	266	266			4 P	268	264
	5					5		

# State of Practice

1031/023/

RCS

2 000/00:03:34  
000/00:00:00

RCS FWD 1\* PRI JET  
L 2 4 FAIL LIM 2  
R 3

OMS PRESS ENA  
L OMS 5 OMS ⇒ RCS QTY  
R OMS 6 L 0.00  
OFF 7\* R 0.00

JET	FAIL	DES INH	JET DES	PTY
F1L		8	9	2
3L		10	11	1
Y 2R		12	13	2
4R		14	15	1
F1U		16	17	2
3U		18	19	1
Z 2U		20	21	3
F1D		22	23	2
3D		24	25	1
2D		26	27	2
4D		28	29	1
F1F		30	31	1
X 3F		32	33	3
2F		34	35	2
F5L		36	37	
V 5R		38	39	

		OXID	FU
HE	P	3256	3392
PRPLT TK	P	267	271
	T	70	70
	QTY	96	96
MANF P	1	268	269
	2	267	270
	3	266	270
	4	267	272
MANF VLVS		STAT	OVRD
	1	OP	40
	2	OP	41
	3	OP	42
	4	OP	43
	5	OP	44
XFEED	P		
JET RESET	45		

# Problem

- Busy
- Many displays available
- Massive amounts of cryptic data
- Repetitive, usually nothing breaks
- Changes are subtle
- Notification of anomaly is subtle
- Fatigue, decreased vigilance, complacency

# Possible Solutions

- Task-oriented display redesign
- Automate

# Possible Solutions

- Task-oriented display redesign
- Automation problems
  - Complex systems
  - Complex interaction of components
  - Model fidelity
  - Sensor limitations
  - OOTLF (Out of the loop familiarity)

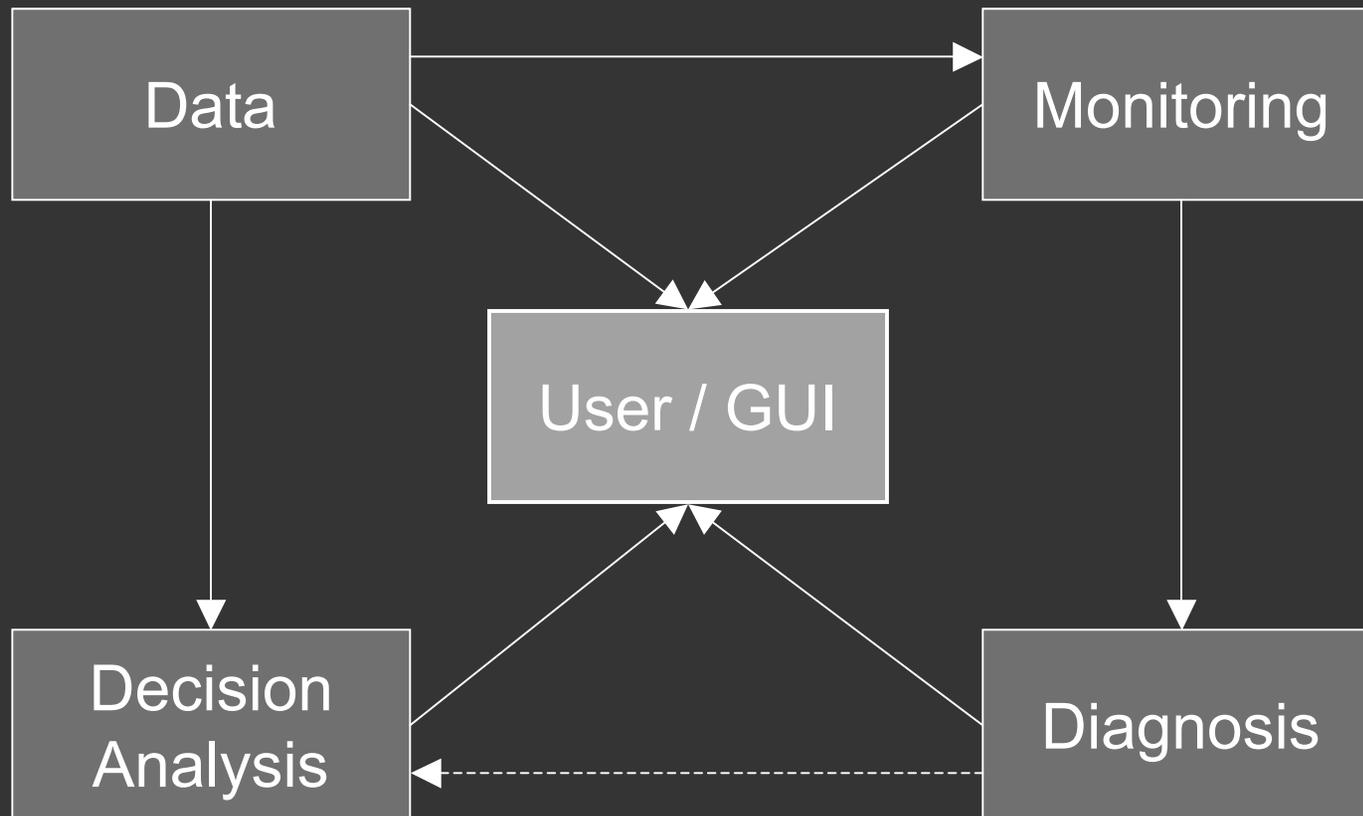
# Possible Solutions

- Task-oriented display redesign
- Automation problems
  - Complex systems
  - Complex interaction of components
  - Model fidelity
  - Sensor limitations
  - OOTLF (Out of the loop familiarity)
- Coordinate automation with human participation

# IDAT

- Operational concept in the embodiment of a tool
- Decision support tool that works in tandem with crew
- Assists crew with uncertain cause or variable context
- Provides germane information

# IDAT Prototype Overview



# State of Practice

1031/ /019 GNC SYS SUMM 2

5 000/00:03:34

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	4 P	266	266			4 P	268	264
	5					5		

MPS	F RCS	L OMS	L RCS	R RCS	R OMS
OK	OK	OK	OK	OK	OK

[Details](#) [Details](#) [Details](#) [Details](#)

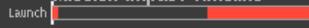
Problems

L RCS LEAK - FUEL

Mission Impact

May lose all LEFT AFT RCS jets. Minimum required at ET-SEP = 1, else orbiter recontact is possible.

Mission Impact Timeline

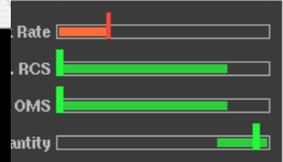
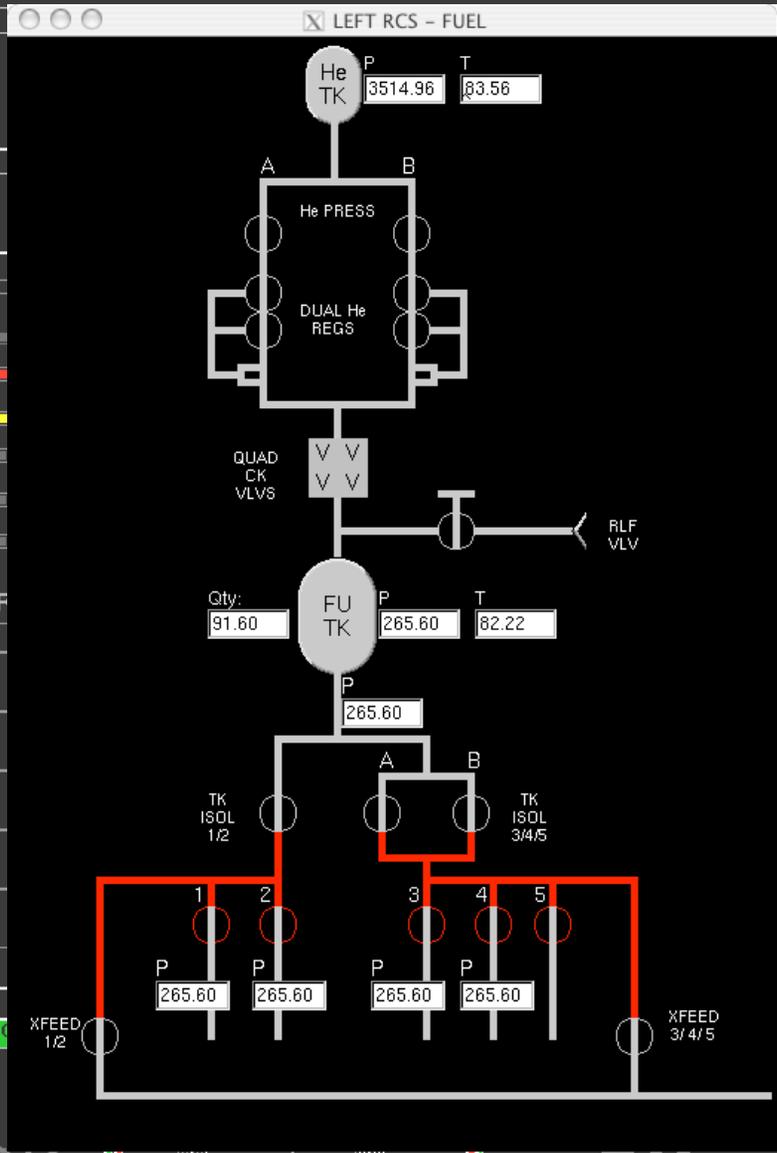


Root Cause Options

- A** Lracs Fu manf 1.5 leak
- B** L Fu xfeed vlv1/2 or xfeed vlv3/4/5 leak
- C** Lracs Fu tk, quad ck vlvs, or relief vlv leak
- D** Lracs FUEL tk isol vlv 1/2, vlv 3/4/5a, or 3/4/5b lk
- E** Lracs Fu manf vlv 1.5 leak

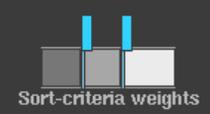
Mitigation Options (Auto-F)

	Option
<b>1</b>	Ignore
<b>2</b>	Xfeed
<b>3</b>	Isolate
<b>4</b>	Isolct
<b>5</b>	Abort



low 75%

Time to ET-SEP 06:54



Constraints


MPS

FRCS

L RCS

XFEED 1/2

Fuel

Oxi

XFEED 3/4/5

R OMS

OK

OK

OK

OK

OK

Problems

L RCS LEAK - FUEL



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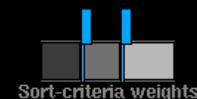
Do NOT:

Do not allow prop level to decrease below 75%. Jet damage may occur. Prop level now = 95%.

Mission Impact Timeline



Root Cause Options



Mitigation Options (Auto-Ranked)

	Option	Pros	Expand	Cons	Constraints
1	Xfeed	Green, Yellow, Green		Yellow	
2	Isolate	Green, Yellow, Green		Yellow	
3	Ignore	Yellow, Yellow, Green		Yellow, Yellow	
4	Ignct	Green, Yellow, Green		Yellow	
5	Abort	Yellow, Green		Yellow, Red	



Problems

L RCS LEAK - FUEL



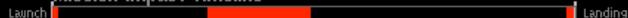
Mission Impact

May lose all LEFT AFT RCS jets. Minimum required at ET-SEP = 1, else orbiter recontact is possible.

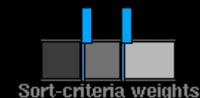
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Mission Impact Timeline



Root Cause Options



Mitigation Options (Auto-Ranked)

	Option	Pros	Cons	Constraints
1	Xfeed	Some Resources; Low crewfactor; No Damage;		
2	Isolate	Some Resources; Low crewfactor; No Damage;		
3	Ignore	No Damage;	Many Resources; No Damage; High	
4	Isolct	Some Resources; Low crewfactor; No Damage;		
5	Abort	Low crewfactor; No Damage;	Many Resources; No Damage;	



Problems

L RCS LEAK - FUEL



Mission Impact

May lose all LEFT AFT RCS jets. Minimum required at ET-SEP = 1, else orbiter recontact is possible.

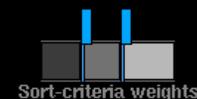
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Mission Impact Timeline



Root Cause Options



Mitigation Options (Auto-Ranked)

	Option	Pros	Expand	Cons	Constraints
1	Xfeed	Green, Yellow, Green		Yellow	
2	Isolate	Green, Yellow, Green		Yellow	
3	Ignore	Yellow, Yellow, Green		Yellow, Yellow	
4	Icnct	Green, Yellow, Green		Yellow	
5	Abort	Yellow, Green		Yellow, Red	



Problems

L RCS LEAK - F

Mission Impact

May lose all LEFT  
Minimum required  
else orbiter recon

Mission Impa

Launch

Root Cause

- A Lrcs Fu manif 1..5
- B L Fu xfeed vlv1/2  
xfeed vlv3/4/5 le
- C Lrcs Fu tk, quad  
relief vlv leak
- D Lrcs FUEL tk Isol  
vlv 3/4/5a, or 3/
- E Lrcs Fu manif vlv

Mitigation Op

- 1 Xfeed
- 2 Isolate
- 3 Ignore
- 4 Icncr
- 5 Abort

Selected Option: Isolate

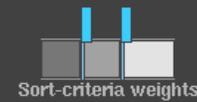
RCS Secure

AFT RCS LK



75%

ET-SEP



MPS F RCS

OK

F RCS

OK

F RCS

OK

LEAK - FUEL

OK

F RCS

OK

R OMS

OK

Details



Details



Details



Details

Problems

L RCS LEAK - FUEL



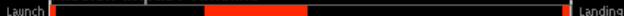
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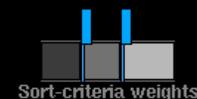
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Mission Impact Timeline



Root Cause Options

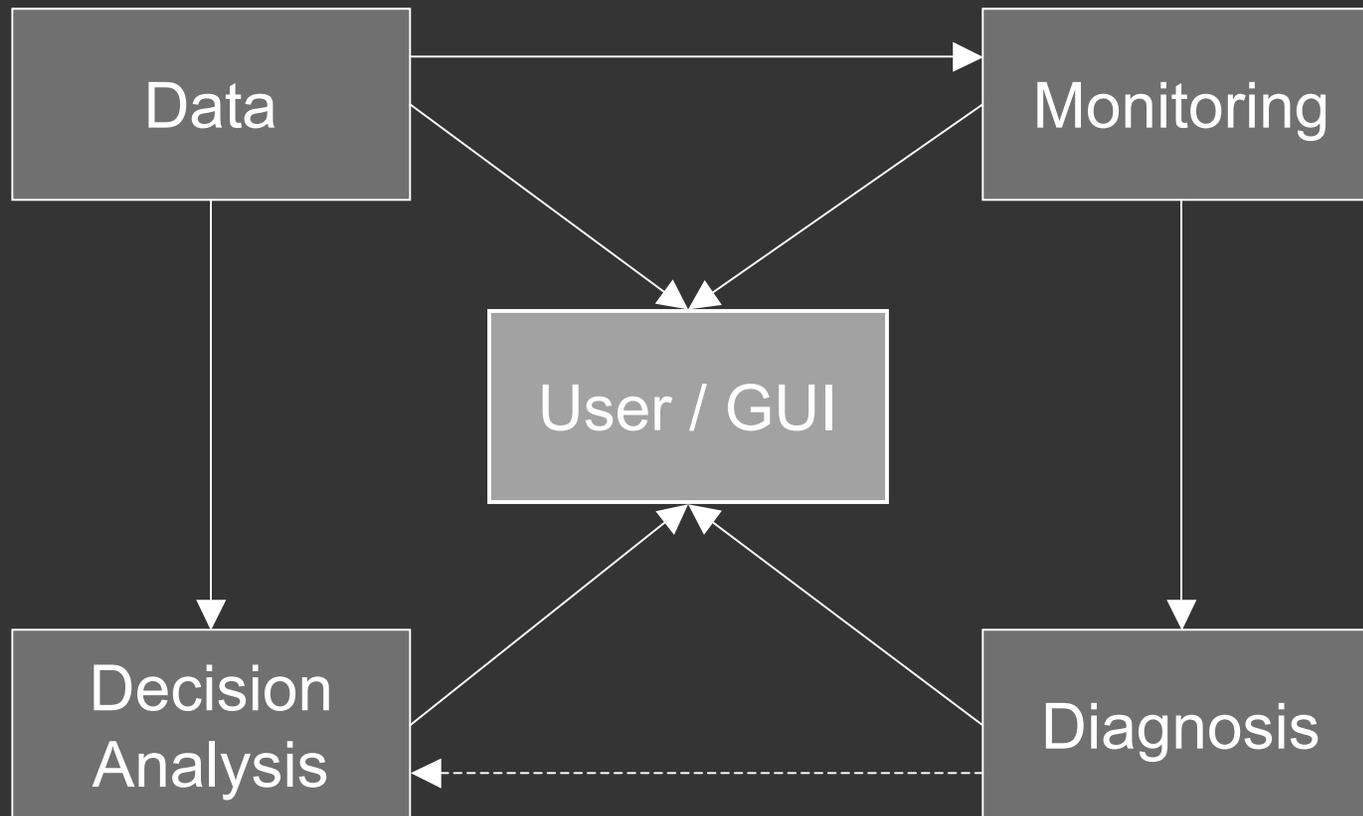


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5	Abort	Yellow, Green		Yellow, Red	



# IDAT Prototype Architecture



Data

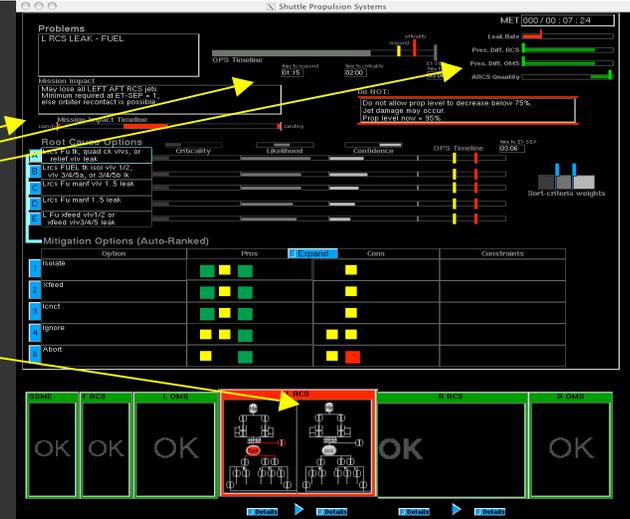
Data

Monitoring

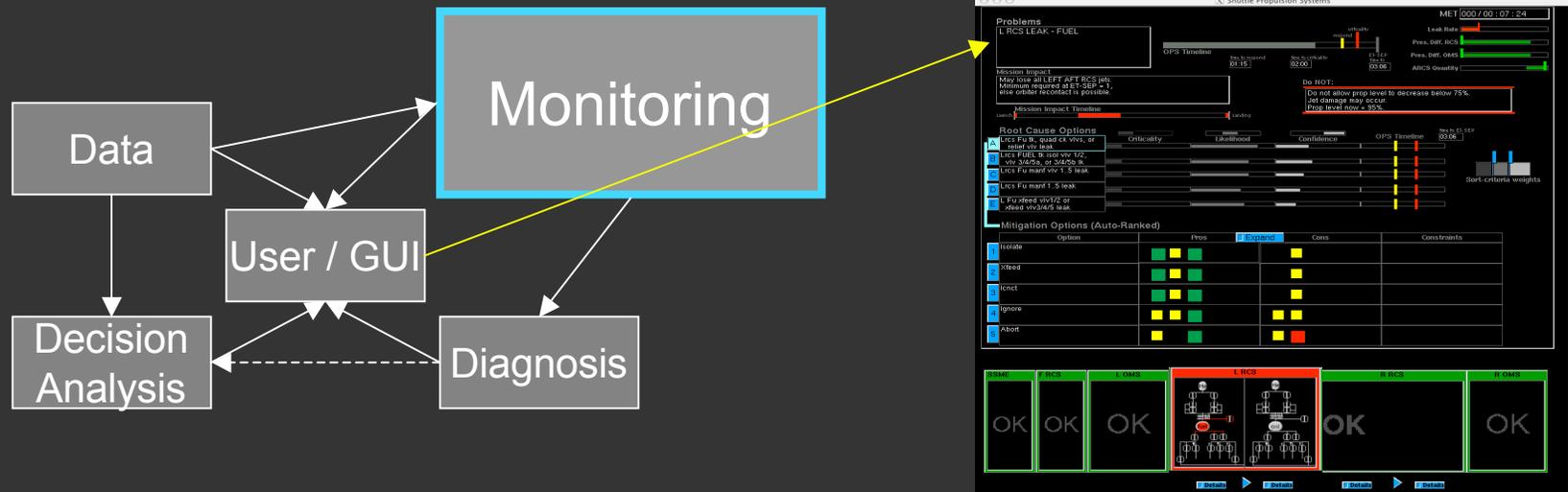
User / GUI

Decision Analysis

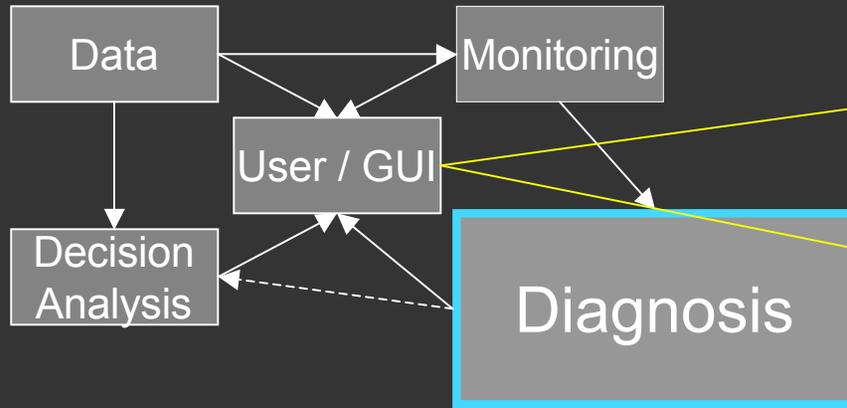
Diagnosis



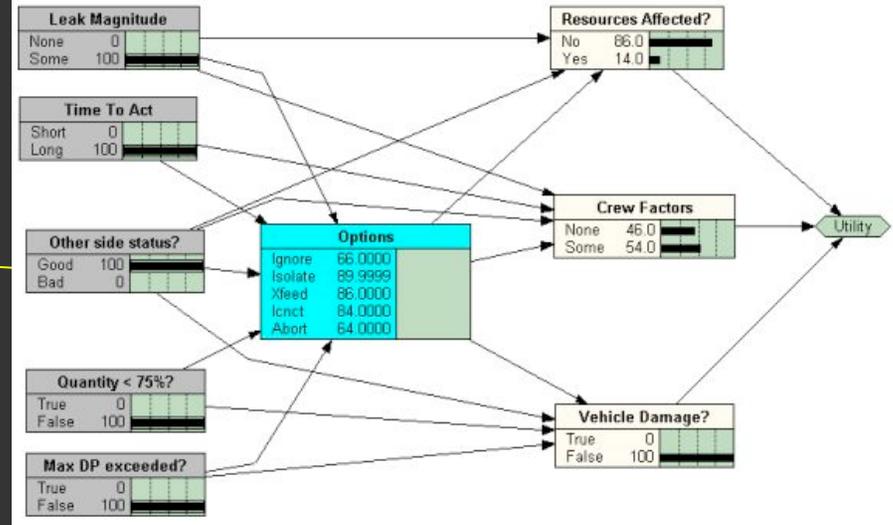
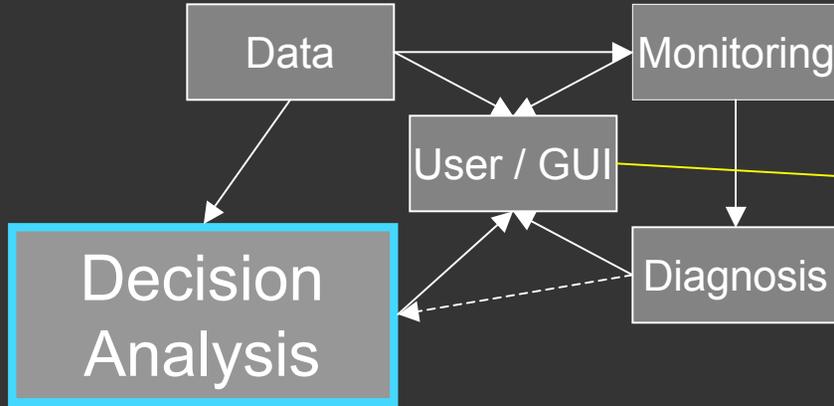
- Purpose: Generate a data stream for concept demonstration
- STS-114 data (RCS parameters, 15 minutes)
- Prototype Challenges
  - Map desired parameter to MSID
  - Multiple configurations (8)
    - Simulate {normal, secure, xfeed, partial xfeed} X {ok, leak}
    - Introduce a leak
    - Transition between configurations
- Appears on UI as:
  - Relevant cues, OPS Timeline
  - State of schematic components
  - “Mission Impact Timeline” (representative data)



- Purpose: Monitor incoming data for anomalous behavior
- Implementation: (Substitute system) Looks for a leak, only
- Appears on UI as:
  - Causes IDAT to appear
  - “Problem” section



- Purpose: Identify root cause(es) of anomalous situation
- Implementation: (Substitute system) Hand-coded
- Appears on UI as
  - “Root Cause Options” section
    - Likelihood and confidence
    - Currently provides criticality, time to respond, and time to criticality
  - State of schematic components per root cause



- Purpose: Rank mitigation options for highest utility
- Mitigation options {ignore, isolate, xfeed, icnct, abort}
- Basic model in Netica
  - 5 inputs {leak rate, ttc, press. diff, prop. quantity, other RCS state}
  - 3 expert-knowledge nodes {resources used, vehicle damage, crew factor}
- Issues
  - Parameter optimization
  - Does not take diagnosis into account
- Appears on UI as “Mitigation Options” section:
  - Options ranked by utility
  - Pros & Cons encode expert-knowledge node values

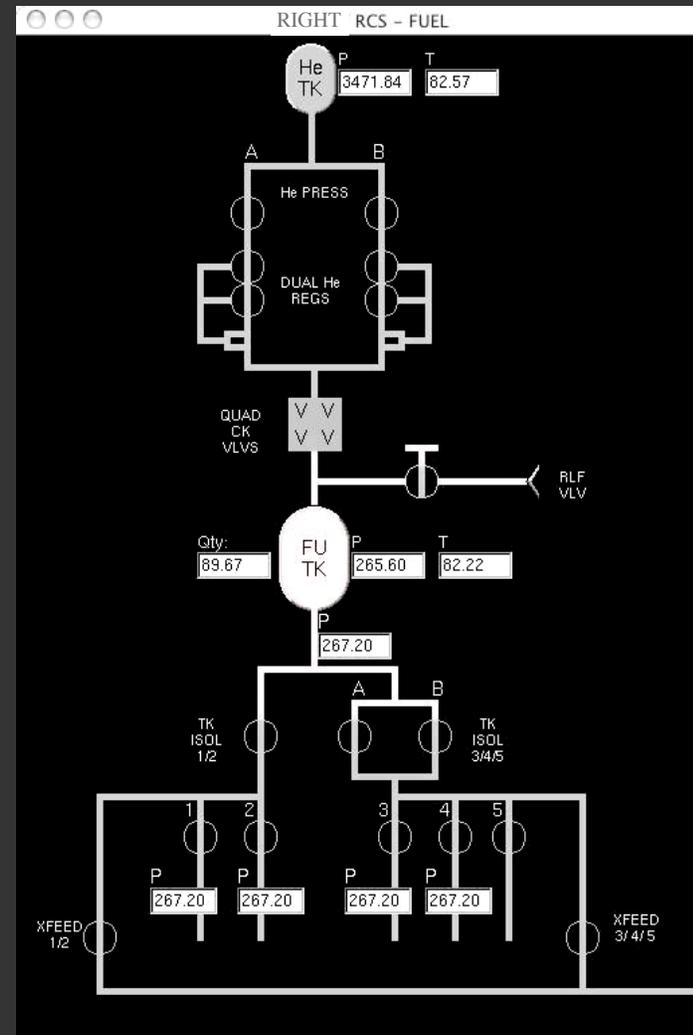
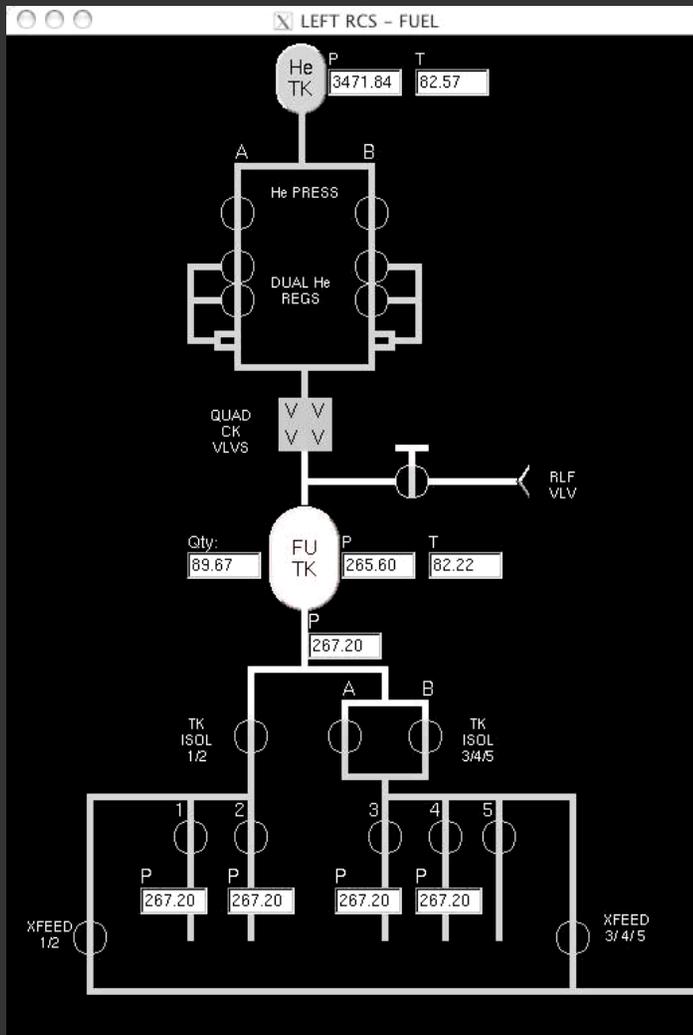
# Summary

- Operational concept for C&W under uncertainty
- Prototype system that presents information to help crew
  - Resolve ambiguity of multiple root causes
  - Determine method for mitigating problem
- Evolving discussion
  - Many issues remain to be resolved
  - User involvement necessary
  - Tie it into operational concept for overall C&W

# Future Work

- User Interaction
- Data System
- Diagnosis System
- Decision Support System
- Mitigation Procedures
- Human Factors (Display)
- Operations concept for C&W system

# Scenario



# IDAT DEMO